

Amendments to the Abstract:

Please replace the abstract with the following new abstract:

In a constant velocity universal joint including a double roller type roller unit, a cylindrical surface is formed in a radially outer surface of the outer roller; a flat engagement surface which is engaged with the cylindrical surface is formed in each of the guide grooves of the outer joint member; and the cylindrical surface satisfies following two equations, $W1 > PCR (1 - \cos\theta) / 2 + \mu_3 R3 + \mu_2 R1$, $W2 > 3PCR (1 - \cos\theta) / 2 - \mu_3 R3 + \mu_2 R1$, wherein W1, W2: a length from a center of the cylindrical surface to each of axially both end portions; PCR: a distance from an axis of the inner joint member to a center of the convex sphere of each of the leg shafts; θ : a required maximum joint angle; R1, R3: radii of the cylindrical surface and the concave sphere, respectively; and μ_2 , μ_3 : friction coefficients between the inner roller and the outer roller, and between the convex sphere and the concave sphere, respectively.